ARM Cortex-M System Timer (SysTick)

Embedded Systems with ARM Cortex-M Microcontrollers in Assembly Language and C

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Visit book website: web.eece.maine.edu/~zhu/book/

System Timer (SysTick)

Generate SysTick interrupts at a fixed time interval





Example Usages:

- Measuring time elapsed, such as time delay function
- Executing tasks periodically, such as periodic polling, and OS CPU scheduling

System Timer (SysTick)

- System timer is a standard hardware component built into ARM Cortex-M.
- This hardware periodically forces the processor to execute the following ISR:

void SysTick_Handler(void){



. . .

Diagram of System Timer (SysTick)



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SysTick Interrupt Time Period = (SysTick_LOAD + 1) × Clock Period = 7 × Clock Period

Diagram of System Timer (SysTick)



Diagram of System Timer (SysTick)



Registers of System Timer

SysTick control and status register (SysTick_CTRL)



SysTick current value register (SysTick_VAL)

31	24 23		0
		CURRENT	

SysTick reload value register (SysTick_LOAD)

SysTick calibration register (SysTick_CALIB)



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Registers of System Timer

SysTick reload value register (SysTick_LOAD)



- 24 bits, maximum value 0x00FF.FFFF (16,777,215)
- Counter counts down from RELOAD value to 0.
- Writing RELOAD to 0 disables SysTick, independently of TICKINT
- Time interval between two SysTick interrupts

```
Interval = (RELOAD + 1) × Source_Clock_Period
```

If 100 clock periods between two SysTick interrupts

RELOAD = 99

Registers of System Timer

SysTick current value register (SysTick_VAL)



- Reading it returns the current value of the counter
- When it transits from 1 to 0, it generates an interrupt
- Writing to SysTick_VAL clears the counter and COUNTFLAG to zero
 - Cause the counter to reload on the next timer clock
 - But, does not trigger an SysTick interrupt
- It has random value on reset.
 - Always clear it before enabling the timer

SysTick calibration register (SysTick_CALIB)



- A read-only register
- > TENMS (10 ms) holds the reload value, which will yield a 10ms period
- May not be implemented or may be defined differently by chip designers

Example Code

```
void SysTick Initialize (uint32 t ticks) {
   SysTick->CTRL = 0; // Disable SysTick
   SysTick->LOAD = ticks - 1; // Set reload register
   // Set interrupt priority of SysTick to least urgency (i.e., largest priority value)
   NVIC SetPriority (SysTick IRQn, (1<< NVIC PRIO BITS) - 1);
                    // Reset the SysTick counter value
   SysTick->VAL = 0;
   // Select processor clock: 1 = processor clock; 0 = external clock
   SysTick->CTRL |= SysTick_CTRL_CLKSOURCE;
   // Enables SysTick interrupt, 1 = Enable, 0 = Disable
   SysTick->CTRL |= SysTick CTRL TICKINT;
   // Enable SysTick
   SysTick->CTRL |= SysTick CTRL ENABLE;
```

Implementing Delay Function

```
volatile int32_t TimeDelay;
```

```
int main (void {
 SysTick_Initialize(1000); // Interrupt period = 1000 cycles
 Delay(100);
              // Delay 100 ticks
  . . .
void SysTick_Handler (void) { // SysTick interrupt service routine
 if (TimeDelay > 0) // Prevent it from being negative
   TimeDelay--; // TimeDelay is a global volatile variable
void Delay (uint32 t nTime) {
 // nTime: specifies the delay time length
 TimeDelay = nTime; // TimeDelay must be declared as volatile
 while(TimeDelay != 0); // Busy wait
```

Calculating Reload Value

- Suppose clock source = 80MHz
- Goal: SysTick Interval = 10ms
- What is RELOAD value?

 $Reload = \frac{10 \, ms}{Clock \, Period} - 1$

- $= 10ms \times Clock Frequency 1$
- $= 10ms \times 80MHz 1$
- $= 10 \times 10^{-3} \times 80 \times 10^{6} 1$
- = 800000 1
- = 799999

